Exercises - The x86-TSO model

1. Peterson algorithm is a classic solution to the *mutual exclusion* problem: in all executions, the instructions of the critical sections of the two threads are not interleaved.

```
flag1 = false;
flag0 = true; flag1 = true;
turn = 1; turn = 0;
while (flag1 && turn == 1); || while (flag0 && turn == 0);
// critical section // critical section
... // end of critical section // end of critical section
flag0 = false; flag1 = false;
```

- (a) Assume a sequentially consistent execution model and explain informally why the two threads cannot be inside the critical section at the same time.
- (b) Does Peterson algorithm guarantee mutual exclusion if executed on a multiprocessor machine where store buffers are observable (e.g. x86)? In case, where would you put memory barriers to ensure the correctness of the algorithm?
- 2. In terms of the formal SC semantics:

flag0 = false;

- (a) Give two different transitions, with derivations using the rules in the notes, of the process t1:(x=(y=z)).
- (b) Give a complete transition sequence of the whole-system state <t1:(x=(y=z)), {x=1,y=2,z=3}>. Is it unique?
- (c) By enumerating the possible whole-system transitions (without giving their derivations in detail), or otherwise, prove that <t1:(x=1);y | t2:(y=1);x, {x=0,y=0}> cannot reach a state of the form <t1:0 | t2:0, M>.
- 3. Consider this x86 example. Initially all registers and [x] and [y] are 0.

| Thread O     | Thread 1       | Thread 2       |
|--------------|----------------|----------------|
| MOV [x] <- 1 | MOV EAX <- [x] | MOV [y] <- 1   |
|              | MOV EBX <- [v] | MOV ECX <- [x] |

Finally: Thread 1: EAX=1, Thread 1: EBX=0, Thread 2: ECX=0.

- (a) Is this allowed with respect to an SC semantics?
- (b) Prove whether or not it is allowed with respect to the x86-TSO abstract machine.
- 4. Download and install the litmus tool from http://diy.inria.fr/sources/litmus-5.01.tar.gz (you need OCaml > 3.12.0; documentation available from http://diy.inria.fr/doc/litmus.html). Test the processor of your laptop against the following examples:

| X86 SB                      |   | X86 MB       |                |    |
|-----------------------------|---|--------------|----------------|----|
| { x=0; y=0; }               |   | { x=0; y=0;  | }              |    |
| P0   P1                     | ; | PO           | P1             | ;  |
| MOV [x],\$1   MOV [y],\$1   | ; | MOV [x],\$1  | MOV EAX,[y]    | ;  |
| MOV EAX,[y]   MOV EAX,[x]   | ; | MOV [y],\$1  | MOV EBX,[x]    | ;  |
| exists (0:EAX=0 /\ 1:EAX=0) | ) | exists (1:EA | X=1 /\ 1:EBX=0 | )) |